

Limit behaviour of diffusion in high contrast periodic media and related Markov semigroups

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*This paper is dedicated to the memory of Professor Vassily Zhikov.
Homogenization and high contrast media
were among his favorite subjects.*

Abstract

The goal of the paper is to describe the large time behaviour of a symmetric diffusion in a high-contrast periodic environment and to characterize the limit process under the diffusive scaling. We consider separately the C_0 and L^2 settings.

1 Introduction

The paper deals with the large time behaviour of a diffusion and the corresponding semigroup defined in a high contrast periodic environment. Equivalently, we study the limit behaviour of a diffusion and the corresponding semigroup defined in a high contrast environment with a periodic microstructure on finite time intervals.

Elliptic and parabolic operators with high contrast rapidly oscillating periodic coefficients have been widely studied in homogenization theory. The first rigorous results for parabolic operators of this type were obtained in [6] and [2]. In particular, it was shown that, under proper choice of the scaling coefficient, the homogenized problem contains a non-local in time operator which reflects the so-called memory effect. Later on in [1], with the help of the two-scale convergence technique, the limit problem was written as a coupled system of parabolic PDEs in the space with a higher number of variables. In the works [9], [10] high contrast problems in domains with singular or asymptotically singular periodic geometry were considered. At present, there are many works in the existing mathematical literature that describe the effective behaviour of high contrast periodic media. Under proper scaling, in parabolic problems this usually results in the memory effect while homogenization of spectral problems leads to a non-linear dependence on the spectral parameter.

In this paper we deal with second order divergence form operators in \mathbb{R}^d . Each such an operator is a generator of a Markov semigroup. The corresponding Markov process (generalized diffusion) has continuous trajectories. However, the presence of a non-local term in the effective operator means that the limit dynamics of the coordinate process is not Markov.

The goal of this work is to equip the coordinate process with additional components in such a way that the dynamics of the enlarged process remains Markovian in the limit. We show that it is sufficient to combine the coordinate process with the position of the diffusion on the rescaled period.

In the paper we consider the mentioned problem both in the spaces of continuous functions and in the L^2 framework. In both cases we introduce proper functional spaces, construct the limit semigroup, and prove the semigroup convergence.

We then use these results in order to obtain the convergence in law, in the path space, of the corresponding Markov process. It is interesting to observe that, although in the original processes the additional component is a function of the coordinate process, in the limit process this component is getting independent while the coordinate process becomes coupled with it.

In the L^2 setting, in addition to proving the semigroup convergence, we also describe the spectrum of the generator of the limit semigroup. Then the semigroup convergence in L^2 spaces allows us to provide some information about the limit behaviour of the spectrum of the original operators. In particular, we partly reprove the results on the convergence of the spectra obtained by V.Zhikov in [9] and [11] by means of two-scale convergence technique.

To our best knowledge, the questions considered in this paper have not been studied in the existing literature. In the discrete framework the results on scaling limits of symmetric random walks in a high contrast periodic environment were obtained in our previous work [7].

Our approach essentially relies on the approximation technique developed in [3] and the technique of periodic correctors [5].

2 Problem setup

Consider a symmetric diffusion operator in divergence form

$$A_\varepsilon f(x) = \operatorname{div}(a_\varepsilon(x)\nabla f(x)), \quad a_\varepsilon(x) = \{a_\varepsilon^{ij}(x)\}_{i,j=1}^d, \quad (1)$$

where $a_\varepsilon^{ij}(x)$ are periodic for all $i, j = 1, \dots, d$ with period $[0, 1]^d$. In what follows we identify $[0, 1]^d$ -periodic functions with functions on the unit torus \mathbb{T}^d with a flat metric. We assume that

$$a_\varepsilon(x) = \begin{cases} a_1(\frac{x}{\varepsilon}), & x \in \mathbb{R}^d \setminus \varepsilon G^\sharp, \\ \varepsilon^2 a_2(\frac{x}{\varepsilon}), & x \in \varepsilon G^\sharp, \end{cases} \quad (2)$$

where $G \subset (0, 1)^d$ is a smooth bounded simply connected domain such that $\overline{G} \subset (0, 1)^d$, and G^\sharp is a periodic extension of G in \mathbb{R}^d . We assume furthermore that there exist $\alpha_0 > 0$ and $\alpha_1 \geq \alpha_0$ such that

$$\alpha_0 \mathbf{I} \leq a_1^{ij}(y) \leq \alpha_1 \mathbf{I} \quad \text{if } y \in \mathbb{R}^d \setminus G^\sharp, \quad \alpha_0 \mathbf{I} \leq a_2^{ij}(y) \leq \alpha_1 \mathbf{I} \quad \text{if } y \in G^\sharp. \quad (3)$$

For the sake of brevity we denote $G_\varepsilon^\sharp = \varepsilon G^\sharp$ and $G^c = \mathbb{T}^d \setminus G$. Observe that under our assumptions both the diameter of a periodicity cell and the distance between neighbouring connected components of G_ε^\sharp are of order ε .

Denote by $C_0(\mathbb{R}^d)$ the Banach space of continuous functions that vanish at infinity with the sup norm $\|u\|_C = \max_{x \in \mathbb{R}^d} |u(x)|$.

For each $\varepsilon > 0$ we can interpret A_ε as an unbounded operator in $C_0(\mathbb{R}^d)$ space or in $L^2(\mathbb{R}^d)$ space.

For the presentation simplicity we assume that both a_1 and a_2 are equal to the unit matrix. The case of generic symmetric periodic positive definite matrices $a_1(y)$ and $a_2(y)$ can be addressed in the same way as this special case.

It is well known (see, for instance, [4]) that for any $\varepsilon > 0$ the operator A_ε in $C_0(\mathbb{R}^d)$ is the generator of a strongly continuous positive contraction semigroup $T_\varepsilon(t) = e^{A_\varepsilon t}$. The domain of this operator is dense in $C_0(\mathbb{R}^d)$, the operator is closed, and for any $\lambda > 0$ the resolvent $(\lambda - A_\varepsilon)^{-1}$ is a bounded operator. Moreover, A_ε is the generator of a Markov process with continuous trajectories in \mathbb{R}^d , for this process we use the notation $Y_\varepsilon(t)$, $t \geq 0$.

In $L^2(\mathbb{R}^d)$ we introduce a domain of A_ε by

$$D_H(A_\varepsilon) = \left\{ f \in H^1(\mathbb{R}^d), f \in H^2(G_\varepsilon^\sharp) \cap H^2(\mathbb{R}^d \setminus G_\varepsilon^\sharp), \right. \\ \left. \varepsilon^2 \nabla f(x) \Big|_{\partial G_\varepsilon^\sharp} \cdot n^+ = -\nabla f(x) \Big|_{\partial G_\varepsilon^\sharp} \cdot n^- \right\} \quad (4)$$

The last condition on $f \in D_H(A_\varepsilon)$ in (4) is the condition of continuity of the flow $a_\varepsilon \nabla f$ through the boundary $\partial G_\varepsilon^\sharp$.

Then $(A_\varepsilon, D_H(A_\varepsilon))$ is a self-adjoint operator in $L^2(\mathbb{R}^d)$, and for any $\lambda > 0$ the operator $(\lambda - A_\varepsilon)$ is coercive.

We consider separately the C_0 and L^2 settings.

2.1 C_0 -setting

In this section we consider A_ε as an unbounded operator in $C_0(\mathbb{R}^d)$. For the set of continuous functions in \mathbb{R}^d with a compact support we use the notation $C_0^b(\mathbb{R}^d)$. The domain $D(A_\varepsilon)$ of the operator A_ε is the closure in the graph norm of the set of functions

$$\left\{ f \in C_0^b(\mathbb{R}^d), f^+ = f \Big|_{G_\varepsilon^\sharp} \in C^\infty(\overline{G_\varepsilon^\sharp}), f^- = f \Big|_{\mathbb{R}^d \setminus G_\varepsilon^\sharp} \in C^\infty(\overline{\mathbb{R}^d \setminus G_\varepsilon^\sharp}), \right. \\ \varepsilon^2 \nabla f^+(x) \Big|_{\partial G_\varepsilon^\sharp} \cdot n^+ = -\nabla f^-(x) \Big|_{\partial G_\varepsilon^\sharp} \cdot n^-, \\ \left. \operatorname{div}(\varepsilon^2 \nabla f^+(x)) \Big|_{\partial G_\varepsilon^\sharp} = \operatorname{div}(\nabla f^-(x)) \Big|_{\partial G_\varepsilon^\sharp} \right\}. \quad (5)$$

We describe now the limit Markov semigroup and its generator. Denote $E = \mathbb{R}^d \times G^*$, where $G^* = \{\star\} \cup G$, and $\{\star\}$ is a single point set which is identified with G^c . In G^* we introduce the topology generated by open sets in G and δ -neighborhoods of \star defined by $O_\delta(\star) = O_\delta(\partial G)$, $\delta > 0$. Then E is equipped with the product topology. A function $F \in C_0(E)$ can be written in a vector form

$$F(x, \hat{y}) = \begin{cases} f_0(x), & \text{if } x \in \mathbb{R}^d, \hat{y} = \star, \\ f_1(x, y), & \text{if } x \in \mathbb{R}^d, \hat{y} = y \in G \end{cases}$$

with $f_0 \in C_0(\mathbb{R}^d)$, $f_1 \in C_0(\mathbb{R}^d, C(\overline{G}))$, $f_1(x, y)|_{y \in \partial G} = f_0(x)$. With this notation, for any $x \in \mathbb{R}^d$

$$f_0(x) = F(x, \star), \quad f_1(x, y) = F(x, y) \text{ for } y \in G. \quad (6)$$

In what follows we identify a function $F(x, \hat{y})$ with the corresponding vector-function $(f_0(x), f_1(x, y))$.

Let us consider in $C_0(E)$ an unbounded operator of the following form

$$(AF)(x, \hat{y}) = \begin{pmatrix} \Theta \nabla \nabla f_0(x) + \frac{1}{|G^c|} \int_{\partial G} \frac{\partial f_1(x, y)}{\partial n_y^-} d\sigma(y) \\ \Delta_y f_1(x, y) \end{pmatrix}, \quad (7)$$

where a positive defined matrix Θ will be defined later on, $\sigma(y)$ is the element of the surface volume on ∂G , n_y^- is the (inner) normal to ∂G . Using the relation $n^+ = -n^-$ and the Stokes formula one can rewrite the operator (7) as follows:

$$(AF)(x, \hat{y}) = \begin{pmatrix} \Theta \nabla \nabla f_0(x) - \frac{1}{|G^c|} \int_G \Delta_y f_1(x, y) dy \\ \Delta_y f_1(x, y) \end{pmatrix}. \quad (8)$$

We define the domain $D(A)$ of the operator A as a closure in the graph norm of the following set of functions:

$$D_A = \left\{ u_0 \in C_0^\infty(\mathbb{R}^d), u_1 \in C_0^\infty(\mathbb{R}^d; C^\infty(\overline{G})), u_1(x, y)|_{y \in \partial G} = u_0(x), \right. \\ \left. \Delta_y u_1(x, y) \Big|_{y \in \partial G} = \Theta \nabla \nabla u_0(x) + \frac{1}{|G^c|} \int_{\partial G} \frac{\partial u_1(x, y)}{\partial n_y} d\sigma(y) \right\}. \quad (9)$$

Lemma 2.1. *The closure of the operator A is a generator of a strongly continuous, positive, contraction semigroup $T(t)$ on $C_0(E)$.*

Proof. In order to apply the Hille-Yosida theorem, and should make sure that:

- 1) $D(A)$ is dense in $C_0(E)$;
- 2) A is a dissipative operator;
- 3) $\text{Im}(\lambda - A)$ is dense in $C_0(E)$ for some $\lambda > 0$.

The set of functions

$$\mathcal{L} = \left\{ u_0 \in C_0^\infty(\mathbb{R}^d), u_1 \in C_0^\infty(\mathbb{R}^d, C^\infty(\overline{G})), u_1(x, y)|_{y \in \partial G} = u_0(x) \right\} \quad (10)$$

is dense in $C_0(E)$. Then to prove the statement 1) it is sufficient to show that D_A is dense in \mathcal{L} , i.e. for any $\delta > 0$ and for any $u = (u_0, u_1) \in \mathcal{L}$ one can find $\hat{u} = (\hat{u}_0, \hat{u}_1) \in D_A$, such that $\|u - \hat{u}\|_{C(E)} < \delta$. We take $\hat{u}_0 = u_0$ and construct \hat{u}_1 in such a way that the following relation holds:

$$\Delta_y \hat{u}_1(x, y) \Big|_{y \in \partial G} - \frac{1}{|G^c|} \int_{\partial G} \frac{\partial \hat{u}_1(x, y)}{\partial n_y} d\sigma(y) = \Theta \nabla \nabla u_0(x). \quad (11)$$

To this end we set $\tilde{u}_1(x, y) = u_1(x, y)\psi(y) + u_0(x)(1 - \psi(y))$ with

$$\psi \in C_0^\infty(\overline{G}) : \quad \psi(y) \equiv 1 \quad \text{as } y \in G \setminus G_\delta,$$

where $G_\delta = \{y \in \overline{G} : \text{dist}(x, \partial G) < \delta\}$. Then $\tilde{u}_1(x, y)|_{\partial G} = u_0(x)$, $\|u - \tilde{u}\|_{C(E)} < c_1\delta$, and the left hand side in (11) evaluated at \tilde{u} is equal to 0. Let $\chi(y)$ be a $C^\infty(\overline{G})$ function such that $\chi(y)|_{y \in \partial G} = 0$, $\frac{\partial \chi(y)}{\partial n_y} \Big|_{\partial G} = 0$, $\Delta \chi(y) \Big|_{y \in \partial G} = 1$, and $\|\chi\|_{C(\overline{G})} < \delta$. If we take $\hat{u}_1(x, y) = \tilde{u}_1(x, y) + \Theta \nabla \nabla u_0(x)\chi(y)$ then (11) holds and $\|u - \hat{u}\| < c_2\delta$, as required.

The fact that condition 2) holds is a direct consequence of the maximum principle:

$$\|\lambda f - Af\|_{C_0(E)} \geq \lambda \|f\|_{C_0(E)}$$

for any $f \in D(A)$ and any $\lambda > 0$.

The third condition is a consequence of the following statement: there exists $\lambda > 0$ such that for any $g = (g_0, g_1) \in C_0(E)$ the equation $(\lambda - A)f = g$ has a solution $f \in D(A)$. To prove this statement we use (8) and rewrite the equation $(\lambda - A)f = g$ as follows

$$\lambda f_0 - \Theta \nabla \nabla f_0(x) - \frac{1}{|G^c|} \int_{\partial G} \frac{\partial f_1(x, y)}{\partial n_y} d\sigma(y) = g_0(x), \\ \lambda f_1 - \Delta_y f_1(x, y) = g_1(x, y). \quad (12)$$

Since the latter system is linear, $f_1(x, y)$ is a sum of the solutions of the following two problems:

$$\begin{cases} \lambda f_1^I - \Delta_y f_1^I(x, y) = 0, \\ f_1^I(x, y) \Big|_{y \in \partial G} = f_0(x), \end{cases}$$

and

$$\begin{cases} \lambda f_1^H - \Delta_y f_1^H(x, y) = g_1(x, y), \\ f_1^H(x, y)|_{y \in \partial G} = 0. \end{cases}$$

Then the solution of the former problem takes the form $f_1^I(x, y) = f_0(x)\varphi(y)$, where $\varphi(y)$ satisfies the equation $(\lambda - \Delta_y)\varphi(y) = 0$ in G , and the boundary condition $\varphi(y)|_{y \in \partial G} = 1$ on ∂G . The solution $f_1^H(x, y)$ of the latter problem is a continuous function of x and y that vanishes as $x \rightarrow \infty$. The function

$$f_1(x, y) = f_0(x)\varphi(y) + f_1^H(x, y) \quad (13)$$

satisfies the second equation in (12) and the boundary condition $f_1(x, y)|_{y \in \partial G} = f_0(x)$. Inserting $f_1(x, y)$ into the first equation in (12) yields the following equation for f_0 :

$$\lambda f_0 - \Theta \nabla \nabla f_0(x) - \widehat{\lambda}_0 f_0(x) = \tilde{g}_0(x).$$

with

$$\widehat{\lambda}_0 = \frac{1}{|G^c|} \int_{\partial G} \frac{\partial \varphi(y)}{\partial n_y} d\sigma(y), \quad \tilde{g}_0(x) = g_0(x) + \frac{1}{|G^c|} \int_G \Delta_y f_1^H(x, y) dy$$

Since $\Delta_y f_1^H(x, y) = \lambda f_1^H - g_1(x, y)$, then $\tilde{g}_0 \in C_0(\mathbb{R}^d)$. Therefore, for any $\lambda > \widehat{\lambda}_0$ the latter equation has a solution $f_0(x) \in C_0(\mathbb{R}^d)$. Then f_1 defined in (13) belongs to $C_0(\mathbb{R}^d; C(\overline{G}))$, and we conclude that $(f_0, f_1) \in D(A)$. Therefore, the Hille-Yosida theorem applies, and the desired statement follows. \square

Corollary 1. *For any $\lambda > \widehat{\lambda}_0$ the set $\{(\lambda - A)F : F \in D_A\}$ is dense in $C_0(E)$.*

Proof. Consider equation (12) and choose a function $G = (g_0, g_1)$ on the right hand side such that $g_0 \in C_0^\infty(\mathbb{R}^d)$, $g_1 \in C_0^\infty(\mathbb{R}^d, C^\infty(\overline{G}))$. By the same arguments as in the proof of Lemma 2.1, we conclude that the corresponding solution $F = (f_0, f_1)$ of problem (12) belongs to the Schwartz class in x , i.e. $f_0 \in \mathcal{S}(\mathbb{R}^d)$, $f_1 \in \mathcal{S}(\mathbb{R}^d, C^\infty(\overline{G}))$.

For any $n \in \mathbb{Z}^+$ denote by φ_n a $C_0^\infty(\mathbb{R}^d)$ cut-off function such that

$$0 \leq \varphi_n \leq 1, \quad \text{supp } \varphi_n \subset \{x : |x| \leq n + 1\}, \quad \varphi_n = 1 \text{ if } |x| \leq n, \quad |\nabla \varphi_n| \leq 2.$$

Then the function $\psi_n = 2\Theta \nabla f_0 \nabla \varphi_n + f_0 \Theta \nabla \nabla \varphi_n$ is an element of $C_0^\infty(\mathbb{R}^d)$, and, moreover, $\|\psi_n\|_{C(\mathbb{R}^d)} \rightarrow 0$, as $n \rightarrow \infty$. Let $\gamma(y)$ be a $C^\infty(\overline{G})$ function such that $\gamma|_{\partial G} = 0$, $\nabla \gamma|_{\partial G} = 0$, $\Delta \gamma|_{\partial G} = 1$. It is clear that

$$F_n = (\varphi_n(x)f_0(x), \varphi_n(x)f_1(x, y) + \gamma(y)\psi_n(x)) \in D_A$$

and that

$$\varphi_n(x)f_0(x) \in C_0^\infty(\mathbb{R}^d), \quad \varphi_n(x)f_1(x, y) + \gamma(y)\psi_n(x) \in C_0^\infty(\mathbb{R}^d, C^\infty(\overline{G})).$$

Now straightforward computations show that $\|AF_n - G\|_{C_0(E)} \rightarrow 0$, as $n \rightarrow \infty$. \square

Remark 2.1. *It follows from Corollary 1 that D_A defined in (9) is a core of the operator A in $C_0(E)$.*

Define a bounded linear transformation $\pi_\varepsilon : C_0(E) \rightarrow C_0(\mathbb{R}^d)$ as follows:

$$(\pi_\varepsilon F)(x) = \begin{cases} f_0(x), & \text{if } x \in \mathbb{R}^d \setminus G_\varepsilon^\sharp; \\ f_1(x, \{\frac{x}{\varepsilon}\}), & \text{if } x \in G_\varepsilon^\sharp. \end{cases} \quad (14)$$

here $\{\cdot\}$ stands for the fractional part. Then for all $\varepsilon \in (0, 1)$

$$\sup_{x \in \mathbb{R}^d} |\pi_\varepsilon F(x)| = \|\pi_\varepsilon F\|_{C_0(\mathbb{R}^d)} \leq \max_{k=0,1} \|f_k\| = \|F\|_{C_0(E)}.$$

We are going to prove the semigroup convergence using the approximation theorem from [3] and correctors for the appropriate diffusions in periodic environment.

Theorem 2.1. *For every $F \in C_0(E)$*

$$T_\varepsilon(t)\pi_\varepsilon F \rightarrow T(t)F \quad \left(\text{i.e. } \|T_\varepsilon(t)\pi_\varepsilon F - \pi_\varepsilon T(t)F\|_{C_0(\mathbb{R}^d)} \rightarrow 0 \right) \quad \text{for all } t \geq 0 \quad (15)$$

as $\varepsilon \rightarrow 0$.

The proof of (15) relies on the following approximation theorem [3, Theorem 6.1, Ch.1].

Theorem (see [3]). *For $n = 1, 2, \dots$, let $T_n(t)$ and $T(t)$ be strongly continuous contraction semigroups on Banach space \mathcal{L}_n and \mathcal{L} , with generators A_n and A . Let D be a core for A . Then the following are equivalent:*

- a) *For each $f \in \mathcal{L}$, $T_n(t)\pi_n f \rightarrow T(t)f$ for all $t \geq 0$.*
- b) *For each $f \in D$, there exists $f_n \in \mathcal{L}_n$ for each $n \geq 1$ such that $f_n \rightarrow f$ and $A_n f_n \rightarrow Af$.*

According to this theorem the semigroups convergence (15) is a consequence of the following statement:

Lemma 2.2. *Let the generators A and A_ε of the strongly continuous, positive, contraction semigroups $T(t)$ and $T_\varepsilon(t)$ be defined by (7) and (1), (2), (5), respectively, and let a core $D_A \subset C_0(E)$ of the generator A be defined by (9).*

Then for any $F = (f_0, f_1) \in D_A$, there exists $F_\varepsilon \in D(A_\varepsilon)$ such that

$$\|F_\varepsilon - \pi_\varepsilon F\|_{C_0(\mathbb{R}^d)} \rightarrow 0 \quad \text{and} \quad \|A_\varepsilon F_\varepsilon - \pi_\varepsilon AF\|_{C_0(\mathbb{R}^d)} \rightarrow 0, \quad \text{as } \varepsilon \rightarrow 0, \quad (16)$$

where $\pi_\varepsilon : C_0(E) \rightarrow C_0(\mathbb{R}^d)$ is a bounded linear transformation defined by (14).

Proof. The proof relies on the correctors technique widely used in the homogenization theory. In order to make (16) hold we construct the following family of functions F_ε :

$$F_\varepsilon(x) = \begin{cases} f_0(x) + \varepsilon(\nabla f_0(x), h(\frac{x}{\varepsilon})) + \varepsilon^2(\nabla \nabla f_0(x), g(\frac{x}{\varepsilon})) + \varepsilon^2 \Phi(x, \frac{x}{\varepsilon}), & x \in \mathbb{R}^d \setminus G_\varepsilon^\sharp, \\ f_1(x, \frac{x}{\varepsilon}) + \varepsilon \phi_\varepsilon(x, \frac{x}{\varepsilon}), & x \in G_\varepsilon^\sharp, \end{cases} \quad (17)$$

where $h(\xi), g(\xi), \Phi(x, \xi)$ and $\phi_\varepsilon(x, \xi)$ are periodic smooth functions of ξ (so-called correctors) defined on the periodicity cell, $h(\xi)$ is the periodic vector function, $g(\xi)$ is the periodic matrix function. A corrector $\phi_\varepsilon(x, \xi)$ has been introduced in order to ensure the continuity of the function F_ε on the boundary $\partial G_\varepsilon^\sharp$. In addition, the functions $\Phi(x, \xi)$, $\phi_\varepsilon(x, \xi)$ are smooth in x and tend to zero as $x \rightarrow \infty$. Moreover, $\|\phi_\varepsilon\|_{C_0^2(\mathbb{R}^d \times \overline{G})} \leq C$ with a constant C that does not depend on ε .

The structure (17) of the function F_ε immediately implies the first convergence in (16):

$$\sup_x |F_\varepsilon(x) - \pi_\varepsilon F(x)| = O(\varepsilon) \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

In order to justify the second convergence in (16) we deduce from (7) and (14) that, for each $\varepsilon > 0$,

$$\|A_\varepsilon F_\varepsilon - \pi_\varepsilon AF\|_{C_0(\mathbb{R}^d)} =$$

$$\max \left\{ \max_{x \in \mathbb{R}^d \setminus G_\varepsilon^\sharp} |A_\varepsilon F_\varepsilon(x) - (\Theta \cdot \nabla \nabla f_0(x) + \Upsilon(x))|, \max_{x \in G_\varepsilon^\sharp, \xi \in G} |A_\varepsilon F_\varepsilon(x) - \Delta_\xi f_1(x, \xi)| \right\}, \quad (18)$$

where $\Upsilon(x) = \frac{1}{|G^c|} \int_{\partial G} \frac{\partial f_1(x, \xi)}{\partial n_\xi} d\sigma(\xi)$. Thus we have to prove that both terms on the right-hand side of (18) tend to 0 as $\varepsilon \rightarrow 0$.

Using (17) and the formula

$$\frac{\partial}{\partial x} f(x, \frac{x}{\varepsilon}) = \left(\frac{\partial}{\partial x} f(x, \xi) + \frac{1}{\varepsilon} \frac{\partial}{\partial \xi} f(x, \xi) \right) \Big|_{\xi = \frac{x}{\varepsilon}},$$

we get

$$\begin{aligned} (A_\varepsilon F_\varepsilon)(x) &= \left(\Delta f_0(x) + 2\nabla \nabla f_0(x) \nabla_\xi h(\xi) \right. \\ &\quad \left. + \frac{1}{\varepsilon} \nabla f_0(x) \Delta_\xi h(\xi) + \nabla \nabla f_0(x) \Delta_\xi g(\xi) + \Delta_\xi \Phi(x, \xi) + \varepsilon \Xi_\varepsilon(x, \xi) \right) \Big|_{\xi = \frac{x}{\varepsilon}}, \end{aligned} \quad (19)$$

if $x \in \mathbb{R}^d \setminus G_\varepsilon^\sharp$, and

$$(A_\varepsilon F_\varepsilon)(x) = \varepsilon^2 \Delta_x \left(f_1(x, \frac{x}{\varepsilon}) + \varepsilon \phi_\varepsilon(x, \frac{x}{\varepsilon}) \right) = \left(\Delta_\xi f_1(x, \xi) + \varepsilon \Psi_\varepsilon(x, \xi) \right) \Big|_{\xi = \frac{x}{\varepsilon}}, \quad (20)$$

if $x \in G_\varepsilon^\sharp$, where

$$\Xi_\varepsilon(x, \xi) = \Delta \nabla f_0(x) \cdot h(\xi) + 2\nabla \nabla \nabla f_0(x) \nabla_\xi g(\xi) + \varepsilon \Delta \nabla \nabla f_0(x) g(\xi) + \varepsilon \Delta_x \Phi(x, \xi) + 2\nabla_x \cdot \nabla_\xi \Phi(x, \xi),$$

and

$$\Psi_\varepsilon(x, \xi) = \varepsilon \Delta_x f_1(x, \xi) + 2\nabla_x \cdot \nabla_\xi f_1(x, \xi) + \varepsilon^2 \Delta_x \phi_\varepsilon(x, \xi) + 2\varepsilon \nabla_x \cdot \nabla_\xi \phi_\varepsilon(x, \xi) + \Delta_\xi \phi_\varepsilon(x, \xi).$$

Moreover, since F_ε should belong to $D(A_\varepsilon)$ the following conditions should be fulfilled for all $x \in \partial G_\varepsilon^\sharp$:

1) the continuity of functions

$$f_0(x) + \varepsilon (\nabla f_0(x), h(\xi)) + \varepsilon^2 (\nabla \nabla f_0(x), g(\xi)) + \varepsilon^2 \Phi(x, \xi) \Big|_{\xi = \frac{x}{\varepsilon}} = f_1(x, \xi) + \varepsilon \phi_\varepsilon(x, \xi) \Big|_{\xi = \frac{x}{\varepsilon}}; \quad (21)$$

2) the continuity of fluxes

$$\begin{aligned} \nabla_x \left(f_0(x) + \varepsilon \left(\nabla f_0(x), h\left(\frac{x}{\varepsilon}\right) \right) + \varepsilon^2 (\nabla \nabla f_0(x), g\left(\frac{x}{\varepsilon}\right)) + \varepsilon^2 \Phi\left(x, \frac{x}{\varepsilon}\right) \right) \Big|_{x \in \partial G_\varepsilon^\sharp} \cdot n^- = \\ -\varepsilon^2 \nabla_x \left(f_1\left(x, \frac{x}{\varepsilon}\right) + \varepsilon \phi_\varepsilon\left(x, \frac{x}{\varepsilon}\right) \right) \Big|_{x \in \partial G_\varepsilon^\sharp} \cdot n^+, \end{aligned}$$

3) the continuity of images

$$\begin{aligned} \operatorname{div} \left(a_1\left(\frac{x}{\varepsilon}\right) \nabla \left(f_0(x) + \varepsilon \left(\nabla f_0(x), h\left(\frac{x}{\varepsilon}\right) \right) + \varepsilon^2 (\nabla \nabla f_0(x), g\left(\frac{x}{\varepsilon}\right)) + \varepsilon^2 \Phi\left(x, \frac{x}{\varepsilon}\right) \right) \right) \Big|_{x \in \partial G_\varepsilon^\sharp} = \\ \varepsilon^2 \operatorname{div} \left(a_2\left(\frac{x}{\varepsilon}\right) \nabla \left(f_1\left(x, \frac{x}{\varepsilon}\right) + \varepsilon \phi_\varepsilon\left(x, \frac{x}{\varepsilon}\right) \right) \right) \Big|_{x \in \partial G_\varepsilon^\sharp}, \end{aligned}$$

where n^+ , n^- are exterior and interior unit normal to ∂G respectively (and $n^+ = -n^-$). The relation in 2) can be rewritten as

$$\begin{aligned} & \left(\nabla f_0(x) + \varepsilon \nabla \nabla f_0(x) h(\xi) + \nabla_\xi (\nabla f_0(x) h(\xi)) + \varepsilon^2 \nabla \nabla \nabla f_0(x) g(\xi) \right. \\ & \quad \left. + \varepsilon \nabla_\xi (\nabla \nabla f_0(x) g(\xi)) + \varepsilon^2 \nabla_x \Phi(x, \xi) + \varepsilon \nabla_\xi \Phi(x, \xi) \right) \Big|_{\xi \in \partial G} \cdot n^- \\ &= - \left(\varepsilon^2 \nabla_x f_1(x, \xi) + \varepsilon \nabla_\xi f_1(x, \xi) + \varepsilon^2 \nabla_\xi \phi_\varepsilon(x, \xi) + \varepsilon^3 \nabla_x \phi_\varepsilon(x, \xi) \right) \Big|_{\xi \in \partial G} \cdot n^+. \end{aligned} \quad (22)$$

To obtain equations on the periodic function $h(\xi)$ we collect the terms of the order ε^{-1} in (19) and of the order ε^0 in (22). This yields

$$\nabla f_0(x) \Delta_\xi h(\xi) = 0, \quad \xi \in G^c, \quad (\nabla f_0(x) + \nabla f_0(x) \nabla_\xi h(\xi)) \cdot n^- = 0, \quad \xi \in \partial G^c. \quad (23)$$

Since f_0 does not depend on ξ , this problem can be rewritten as follows:

$$\Delta h(\xi) = 0, \quad \xi \in G^c, \quad \nabla_\xi h(\xi) \cdot n^- = -n^-, \quad \xi \in \partial G^c, \quad (24)$$

and, in the coordinate form,

$$\Delta h^j(\xi) = 0, \quad \xi \in G^c, \quad \nabla_\xi h^j(\xi) \cdot n^- = -n_j^-, \quad \xi \in \partial G^c.$$

It is easy to check that the compatibility condition is valid:

$$\int_{\partial G^c} n_\xi^- d\sigma(\xi) = 0,$$

consequently, equation (24) has a unique up to an additive constant vector solution $h(\xi)$. Since G is a smooth domain, the function $h(\xi)$ is smooth.

At the next step we collect the terms of order ε^0 on the right-hand side of (19) and equate them to $\Theta \nabla \nabla f_0(x) + \Upsilon(x)$ in order to make the first term in the figure brackets in (18) small:

$$\Delta f_0(x) + 2\nabla \nabla f_0(x) \cdot \nabla_\xi h(\xi) + \nabla \nabla f_0(x) \Delta_\xi g(\xi) + \Delta_\xi \Phi(x, \xi) = \Theta \nabla \nabla f_0(x) + \Upsilon(x). \quad (25)$$

We also collect the terms of order ε^1 in (22):

$$\varepsilon (\nabla \nabla f_0(x) h(\xi) + \nabla_\xi (\nabla \nabla f_0(x) g(\xi)) + \nabla_\xi \Phi(x, \xi)) \Big|_{\xi \in \partial G} \cdot n^- = -\varepsilon \nabla_\xi f_1(x, \xi) \Big|_{\xi \in \partial G} \cdot n^+. \quad (26)$$

Notice that so far the constant matrix Θ and the function Υ have not been specified.

Collecting all the terms in (25)-(26) that contain the second order derivatives of f_0 , we arrive at the following problem for the periodic matrix function $g(\xi)$:

$$\begin{aligned} \Delta f_0(x) + 2\nabla \nabla f_0(x) \cdot \nabla_\xi h(\xi) + \nabla \nabla f_0(x) \Delta_\xi g(\xi) &= \Theta \nabla \nabla f_0(x), \quad \xi \in G^c, \\ (\nabla \nabla f_0(x) h(\xi) + \nabla \nabla f_0(x) \nabla_\xi g(\xi)) \cdot n^- &= 0, \quad \xi \in \partial G^c. \end{aligned}$$

The solvability condition for this problem reads

$$\int_{G^c} (-(E + 2\nabla_\xi h(\xi)) + \Theta) d\xi + \int_{\partial G^c} h(\xi) \otimes n^- d\sigma(\xi) = 0.$$

This allows us to define the constant matrix Θ as follows:

$$\Theta|_{G^c} = \int_{G^c} (E + 2\nabla_\xi h(\xi)) d\xi - \int_{\partial G^c} h(\xi) \otimes n^- d\sigma(\xi). \quad (27)$$

Under relation (27) the function $g(\xi)$ exists and is unique (up to an additional constant matrix).

Let us prove that the matrix Θ is positive definite. Using integration by parts formula, we obtain

$$\int_{G^c} \nabla_\xi h(\xi) d\xi = \int_{\partial G^c} h(\xi) \otimes n^- d\sigma(\xi).$$

Thus, $\Theta|G^c| = \int_{G^c} (E + \nabla_\xi h(\xi)) d\xi$. Since $(E + \nabla_\xi h(\xi))(E + \nabla_\xi h(\xi))^* > 0$, then it is sufficient to show that

$$\int_{G^c} (E + \nabla_\xi h(\xi)) (\nabla_\xi h(\xi))^* d\xi = 0.$$

The last equality follows from integration by parts formula and relation (24) for the function h . Indeed,

$$\int_{G^c} (E + \nabla_\xi h(\xi)) (\nabla_\xi h(\xi))^* d\xi = - \int_{\partial G^c} (E + \nabla_\xi h(\xi)) n^- \otimes h(\xi) d\sigma(\xi) - \int_{G^c} \Delta h(\xi) \otimes h(\xi) d\xi = 0.$$

Collecting the remaining terms in (25) and (26) we obtain the following problem for the function $\Phi(x, \xi)$:

$$\Delta_\xi \Phi(x, \xi) = \Upsilon(x), \quad \xi \in G^c, \quad \nabla_\xi \Phi(x, \xi) \cdot n^- = \nabla_\xi f_1(x, \xi) \cdot n^-, \quad \xi \in \partial G^c. \quad (28)$$

The solvability condition for problem (28) gives the expression for $\Upsilon(x)$:

$$\Upsilon(x)|G^c| = \int_{\partial G} \nabla_\xi f_1(x, \xi) \cdot n_\xi^- d\sigma(\xi) = - \int_{\partial G} \nabla_\xi f_1(x, \xi) \cdot n_\xi^+ d\sigma(\xi). \quad (29)$$

Thus, the function $\Upsilon(x)$ and the solution $\Phi(x, \xi)$ are uniquely defined. Moreover, $\Upsilon \in C_0^\infty(\mathbb{R}^d)$ and $\Phi(x, \xi) \in C_0^\infty(\mathbb{R}^d; C^\infty(G^c))$.

Our expansions have been designed in such a way, that

$$\max_{x \in \mathbb{R}^d \setminus G_\varepsilon^\sharp} |A_\varepsilon F_\varepsilon(x) - (\Theta \cdot \nabla \nabla f_0(x) + \Upsilon(x))| \leq C\varepsilon, \quad \max_{x \in G_\varepsilon^\sharp, \xi \in G} |A_\varepsilon F_\varepsilon(x) - \Delta_\xi f_1(x, \xi)| \leq C\varepsilon.$$

However, the continuity conditions 1) – 3) need not be fulfilled.

The last step of the proof is to define a function $\phi_\varepsilon(x, \xi)$ in such a way that conditions 1) – 3) hold true. The main purpose of this function is to compensate the discrepancy between the inner and the outer expansions for the function F_ε at the boundary $\partial G_\varepsilon^\sharp$. Condition 1) leads to the relation

$$\phi_\varepsilon(x, \xi) = \nabla f_0(x)h(\xi) + \varepsilon \nabla \nabla f_0(x)g(\xi) + \varepsilon \Phi(x, \xi), \quad \xi \in \partial G. \quad (30)$$

The continuity of fluxes condition (condition 2)) reads

$$(\nabla \nabla \nabla f_0(x)g(\xi) + \nabla_x \Phi(x, \xi)) \cdot n^- + (\nabla_x f_1(x, \xi) + \varepsilon \nabla_x \phi_\varepsilon(x, \xi)) \cdot n^+ = -\nabla_\xi \phi_\varepsilon(x, \xi) \cdot n^+, \quad \xi \in \partial G. \quad (31)$$

Here $\nabla_x \phi_\varepsilon(x, \xi)$ can be found from relation (30).

Condition 3) takes the form

$$\Xi_\varepsilon(x, \xi) = \Psi_\varepsilon(x, \xi), \quad \xi \in \partial G; \quad (32)$$

here we have used equations (23), (25), and the fact that $f = (f_0(x), f_1(x, \xi)) \in D_A$. Observe that in the relation (32) all the terms have already been specified except for the term $\Delta_\xi \phi_\varepsilon(x, \xi)$.

Since the boundary ∂G is smooth, we can introduce the local coordinates in the vicinity of ∂G so that one of these coordinates coincides with the normal and the others are coordinates on ∂G . In these coordinates one can extend the function $\phi_\varepsilon(x, \xi)$ to $\mathbb{R}^d \times \overline{G}$ in such a way that it satisfies conditions (30) – (32) and the additional condition

$$\sup_{\xi \in G, x \in \mathbb{R}^d} \{\nabla_\xi \nabla_\xi \phi_\varepsilon, \nabla_x \nabla_\xi \phi_\varepsilon, \nabla_x \nabla_x \phi_\varepsilon\} \leq C_0.$$

This construction is explicit and we leave the details to the reader.

This completes the proof of Lemma 2.2. □

As was explained above, relation (15) is a consequence of Lemma 2.2.

According to the general results, see e.g. [4], there exist Markov processes $Y_\varepsilon(t)$ with continuous trajectories in \mathbb{R}^d (a generalized diffusion process) generated by operators A_ε . In Theorem 2.1 we justified the convergence of the corresponding semigroups, and our next problem is to prove the existence of the limit process $X(t)$ in E with sample paths in $D_E[0, \infty)$ and to prove the convergence of the processes in the Skorokhod topology of $D_E[0, \infty)$. However the process $Y_\varepsilon(t)$ lives in \mathbb{R}^d , and to formulate the statement about convergence of the processes we should first equip the coordinate process $Y_\varepsilon(t)$ with an additional variable $k_\varepsilon(y) \in G^\star$, that specifies the position of $Y_\varepsilon(t)$ in the period \mathbb{T}^d . We define a process $X_\varepsilon(t)$ with trajectories in $E = \mathbb{R}^d \times G^\star$ as follows

$$X_\varepsilon(t) = (Y_\varepsilon(t), k_\varepsilon(Y_\varepsilon(t))), \text{ where } k_\varepsilon(y) = \left\{ \frac{y}{\varepsilon} \right\} \in G \text{ if } y \in G_\varepsilon^\# \text{ and } k_\varepsilon(y) = \star \text{ if } y \in \mathbb{R}^d \setminus G_\varepsilon^\#. \quad (33)$$

Remark 2.2. *The semigroup $T(t)$ introduced in Lemma 2.1 is a Feller semigroup on $C_0(E)$.*

Theorem 2.2. *For any initial distribution $\nu \in \mathcal{P}(E)$ there exists a Markov process $X(t)$ corresponding to the semigroup $T(t) : C_0(E) \rightarrow C_0(E)$ with generator A defined by (7), (9) and with sample paths in $D_E[0, \infty)$.*

If ν is the limit law of $X_\varepsilon(0)$, then $X_\varepsilon(t)$ converges in distribution to $X(t)$ as $\varepsilon \rightarrow 0$ in the Skorokhod topology of $D_E[0, \infty)$:

$$X_\varepsilon(t) \Rightarrow X(t) \quad \text{in } D_E[0, \infty) \text{ as } \varepsilon \rightarrow 0. \quad (34)$$

Proof. To prove convergence (34) we combine the convergence of the finite dimensional distributions of $X_\varepsilon(t)$ (that is a consequence of Theorem 2.1) and the tightness of $X_\varepsilon(t)$ in $D_E[0, \infty)$.

We apply here Theorem 2.11 from [3], Chapter 4. For the reader convenience we formulate it here.

Theorem (see [3]). *Let M, M_1, M_2, \dots be metric spaces with M locally compact and separable. For $n = 1, 2, \dots$ let $\eta_n : M_n \rightarrow M$ be measurable, let $T_n(t)$ be a semigroup on $B(M_n)$ (the Banach space of bounded functions with the sup-norm), and suppose Y_n is a Markov process in M_n corresponding to $T_n(t)$ such that $X_n = \eta_n \circ Y_n$ has sample paths in $D_M[0, \infty)$. Define $\pi_n : B(M) \rightarrow B(M_n)$ by $\pi_n f = f \circ \eta_n$. Suppose that $T(t)$ is a Feller semigroup on $C_0(M)$ and that for each $f \in C_0(M)$ and $t \geq 0$*

$$T_n(t)\pi_n f \rightarrow T(t)f, \quad \text{i.e. } \|T_n(t)\pi_n f - \pi_n T(t)f\| \rightarrow 0. \quad (35)$$

If $\{X_n(0)\}$ has limiting distribution $\nu \in \mathcal{P}(M)$, then there is a Markov process X corresponding to $T(t)$ with initial distribution ν and sample paths in $D_M[0, \infty)$, and $X_n \Rightarrow X$.

We now adapt the constructions of this theorem to our framework. Let $n = \frac{1}{\varepsilon}$, $M_n = \mathbb{R}^d$, $M = E = \mathbb{R}^d \times G^\star$. Define the mapping $\eta_\varepsilon : \mathbb{R}^d \rightarrow E$ as $\eta_\varepsilon : x \rightarrow (x, k_\varepsilon(x))$, where k_ε was given by (33). Then η_ε is the measurable mapping for every ε . The mapping η_ε complements each coordinate $x \in \mathbb{R}^d$ with an additional coordinate $k_\varepsilon(x)$ from G^\star in accordance with (33). Thus, under the mapping η_ε , the image of all points from $\partial G_\varepsilon^\#$ and from $(G_\varepsilon^c)^\#$ has the same second coordinate equal to $\star \in G^\star$. Then $X_\varepsilon = \eta_\varepsilon \circ Y_\varepsilon$ has sample paths in $D_E[0, \infty)$. Moreover, X_ε has continuous sample paths in E . The semigroup $T(t)$ on $C_0(E)$ is the Feller semigroup as was mentioned in the same Remark 2.2. We stress that in this context $C_0(M) = C_0(E)$.

Thus, all the assumptions of [3, Theorem 2.11] are fulfilled, then these processes convergence in law in the space $D_E[0, \infty)$. Theorem 2.2 is completely proved. \square

2.2 L^2 -setting

In this section we consider the limit behaviour of A_ε in L^2 framework. If we set

$$\hat{D}(A_\varepsilon) = \left\{ f \in H^1(\mathbb{R}^d) \cap H^2(G_\varepsilon^\sharp) \cap H^2(\mathbb{R}^d \setminus G_\varepsilon^\sharp), \varepsilon^2 \nabla f(x) \Big|_{\partial G_\varepsilon^\sharp} \cdot n^+ = -\nabla f(x) \Big|_{\partial G_\varepsilon^\sharp} \cdot n^- \right\} \quad (36)$$

where n^-, n^+ are respectively the internal and external normal vectors on $\partial G_\varepsilon^\sharp$, then the operator A_ε with the domain $\hat{D}(A_\varepsilon)$ defined in (36) is a self-adjoint operator in $L^2(\mathbb{R}^d)$. The last condition on $f \in \hat{D}(A_\varepsilon)$ in (36) is the condition of continuity of the flux $a_\varepsilon \nabla f$ at the boundary $\partial G_\varepsilon^\sharp$. By the Hille-Yosida theorem, A_ε is a generator of a strongly continuous, positive, contraction semigroup $T_\varepsilon(t)$ on $L^2(\mathbb{R}^d)$.

We describe now a generator of the limit Markov semigroup. Denote $E = \mathbb{R}^d \times G^*$, and equip G^* with the norm $dy + \delta_\star(\hat{y})$, where $\delta_\star(\hat{y})$ is δ -function at \star . Then a function $F \in L^2(E)$ can be written in a vector form (see (6))

$$F(x, \hat{y}) = (f_0(x), f_1(x, y)), \quad x \in \mathbb{R}^d, \hat{y} \in G^*, y \in G$$

with $f_0 \in L^2(\mathbb{R}^d)$, $f_1 \in L^2(\mathbb{R}^d \times G)$. The norm in $L^2(E)$ is given by

$$\|F\|_{L^2(E)}^2 = \int_{\mathbb{R}^d} f_0^2(x) dx + \int_{\mathbb{R}^d} \int_G f_1^2(x, y) dy dx.$$

Defining an operator A in $L^2(E)$ by formulas (7), (8), one can easily check that, with a domain

$$\hat{D}(A) = \left\{ f_0 \in H^2(\mathbb{R}^d), f_1 \in L^2(\mathbb{R}^d; H^2(G)), f_1(x, y) \Big|_{\partial G} = f_0(x) \right\}, \quad (37)$$

the operator $(A, \hat{D}(A))$ is a closed symmetric operator in $L^2(E)$. Also, $\hat{D}(A)$ is dense in $L^2(E)$.

Lemma 2.3. *For any $m > 0$ the operator $(m - A, \hat{D}(A))$ is a coercive self-adjoint operator in $L^2(E)$.*

Proof. Consider the following quadratic form

$$\Gamma(F) = \int_{\mathbb{R}^d} |\nabla f_0|^2(x) dx + \int_{\mathbb{R}^d} \int_G |\nabla_y f_1|^2(x, y) dy dx + m \|F\|_{L^2(E)}^2 \quad (38)$$

on E with a domain

$$D(\Gamma) = \left\{ f_0 \in H^1(\mathbb{R}^d), f_1 \in L^2(\mathbb{R}^d; H^1(G)), f_1(x, y) \Big|_{\partial G} = f_0(x) \right\}. \quad (39)$$

Notice that $(f_1 - f_0) \in L^2(\mathbb{R}^d; H_0^1(G))$ for any $f \in D(\Gamma)$. According to [8, Theorem x.x] there exists a unique self-adjoint operator \tilde{A}_m on E that has the following properties: its domain $D(\tilde{A}_m)$ is dense in $L^2(E)$; $D(\tilde{A}_m)$ belongs to $D(\Gamma)$; $(\tilde{A}_m U, U) \Big|_{L^2(E)} = \Gamma(U, U)$ for any $U \in D(\tilde{A}_m)$. We are going to show that \tilde{A}_m coincides with $m - A$.

First we prove that $D(\tilde{A}_m) \subset \hat{D}(A)$. Taking $F \in D(\tilde{A}_m)$ and $U = (0, u_1(x, y))$ with $u_1 \in C_0^\infty(\mathbb{R}^d; C_0^\infty(G))$, and using the relation $(\tilde{A}_m F, U)_{L^2(E)} = \Gamma(F, U)$, we obtain $(\tilde{A}_m F, U)_{L^2(E)} = ((m - \Delta_y) f_1, u_1)$ where the right-hand side is understood as a pairing between $L^2(\mathbb{R}^d; H^{-1}(G))$ and $L^2(\mathbb{R}^d; H_0^1(G))$. This implies that $(m - \Delta_y) f_1 \in L^2(\mathbb{R}^d \times G)$ and thus $f_1 \in L^2(\mathbb{R}^d; H^2(G))$. Choosing now $U = (u_0(x), 0)$ with $u_0 \in C_0^\infty(\mathbb{R}^d)$, we get $m f_0 - \operatorname{div}(\Theta \nabla f_0) \in L^2(\mathbb{R}^d)$. Therefore, $f_0 \in H^2(\mathbb{R}^d)$, and $D(\tilde{A}_m) \subset \hat{D}(A)$. Moreover, $\tilde{A}_m F = (m - A)F$ for any $F \in D(\tilde{A}_m)$.

Since \tilde{A}_m is self-adjoint, $D(\tilde{A}_m) = \hat{D}(A)$. This yields the desired statement. \square

As a core for the operator A defined by (7) (see [3, Section 1.3] for the definition of a core) we choose the set D_A defined in (9). Clearly, D_A is a dense subset in $L^2(E)$.

The fact that the set $\{(m - A)F, F \in D_A\}$ is dense in $L^2(E)$ can be justified in the same way as in the proof of Corollary 1.

Applying again the Hille-Yosida theorem, we conclude that A is a generator of a strongly continuous, positive, contraction semigroup $T(t)$ on $L^2(E)$.

The definition of a linear mapping π_ε in the L^2 setting should be slightly modified. Namely, we set

$$(\pi_\varepsilon^H F)(x) = \begin{cases} f_0(x), & \text{if } x \in \mathbb{R}^d \setminus G_\varepsilon^\sharp; \\ \frac{1}{\varepsilon^d |G|} \int_{\varepsilon G} f_1(\hat{x} + \eta, \xi) d\eta, & \text{if } x \in G_\varepsilon^\sharp, \end{cases} \quad (40)$$

where $x = \hat{x} + \varepsilon\xi \in G_\varepsilon^\sharp$, $\hat{x} = \varepsilon \left[\frac{x}{\varepsilon} \right] \in \varepsilon\mathbb{Z}^d \subset \mathbb{R}^d$, $\xi = \left\{ \frac{x}{\varepsilon} \right\} \in G$.

Theorem 2.3. *For every $F \in L^2(E)$*

$$T_\varepsilon(t)\pi_\varepsilon^H F \rightarrow T(t)F \quad \left(\text{i.e. } \|T_\varepsilon(t)\pi_\varepsilon^H F - \pi_\varepsilon^H T(t)F\|_{L^2(\mathbb{R}^d)} \rightarrow 0 \right) \quad \text{for all } t \geq 0 \quad (41)$$

as $\varepsilon \rightarrow 0$.

We use the approximation theorem [Theorem 6.1, Chapter 1, [3]] that was formulated in section 2.1. In order to justify the convergence in (41) it is sufficient to prove the following statement.

Lemma 2.4. *Let the generators A and A_ε of the strongly continuous, positive, contraction semigroups $T(t)$ and $T_\varepsilon(t)$ be defined by (7) and (1), (2), (36), respectively, and assume that a core $D_A \subset L^2(E)$ for the generator A is defined by (9), and that a bounded linear transformation $\pi_\varepsilon^H : L^2(E) \rightarrow L^2(\mathbb{R}^d)$ is defined by (40).*

Then for every $F \in D_A$, there exists $F_\varepsilon \in D(A_\varepsilon)$ such that

$$\|F_\varepsilon - \pi_\varepsilon^H F\|_{L^2(\mathbb{R}^d)} \rightarrow 0 \quad \text{and} \quad \|A_\varepsilon F_\varepsilon - \pi_\varepsilon^H A F\|_{L^2(\mathbb{R}^d)} \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0. \quad (42)$$

Proof. We first show that for any $F = (f_0(x), f_1(x, y)) \in D_A$ with a compact support the following limit relations hold:

$$\|\pi_\varepsilon F - \pi_\varepsilon^H F\|_{L^2(\mathbb{R}^d)} \rightarrow 0, \quad \|\pi_\varepsilon A F - \pi_\varepsilon^H A F\|_{L^2(\mathbb{R}^d)} \rightarrow 0 \quad (43)$$

with π_ε defined in (14). Indeed, due to the definitions of π_ε and π_ε^H , we have $\pi_\varepsilon F - \pi_\varepsilon^H F = 0$ on $\mathbb{R}^d \setminus G_\varepsilon^\sharp$. On G_ε^\sharp the following estimate holds:

$$\max_{x \in G_\varepsilon^\sharp} |(\pi_\varepsilon F)(x) - (\pi_\varepsilon^H F)(x)| \leq \max_{y \in G} \max_{\mathcal{R}_\varepsilon} |f_1(x', y) - f_1(x'', y)| \xrightarrow{\varepsilon \rightarrow 0} 0,$$

where $\mathcal{R}_\varepsilon = \{x', x'' \in \mathbb{R}^d : |x' - x''| \leq \varepsilon\}$; the last convergence is a consequence of the uniform continuity of the function f_1 . This implies the first relation in (43). The second one can be justified in the same way.

We now turn to the proof of Lemma 2.4. As a consequence of formula (16) in Lemma 2.2 we obtain that for any $F = (f_0, f_1) \in D_A$ there exists $F_\varepsilon \in D(A_\varepsilon)$ such that

$$\|F_\varepsilon - \pi_\varepsilon F\|_{L^2(\mathbb{R}^d)} \rightarrow 0 \quad \text{and} \quad \|A_\varepsilon F_\varepsilon - \pi_\varepsilon A F\|_{L^2(\mathbb{R}^d)} \rightarrow 0, \quad \text{as } \varepsilon \rightarrow 0. \quad (44)$$

here we have also used the fact that any function F_ε with a compact support that belongs to the domain of A^ε in the space $C_0(\mathbb{R}^d)$ belongs as well to the domain of A^ε in the space $L^2(\mathbb{R}^d)$.

It remains to combine (44) and (43) and to apply the triangle inequality, then the desired statement follows. \square

We proceed with the description of the spectrum of the limit operator in (7), and then using the strong convergence of Markov semigroup T_ε in $L^2(E)$ obtained above we describe the limit behaviour of the spectrum of operator A_ε , as $\varepsilon \rightarrow 0$. The spectrum of the limit problem and the results on convergence of spectra have been previously obtained by V. Zhikov in [9]. Here we partly reprove these results using the semigroup approach presented above.

First we represent $f_1(x, \xi)$ in (9) as the sum $f_1(x, \xi) = f_0(x) + g_1(x, \xi)$, then $g_1|_{\xi \in \partial G} = 0$. Then the formula in (8) takes the form:

$$-A(f_0(x), f_1(x, \xi)) = \begin{pmatrix} -\Theta \nabla \nabla f_0(x) + \frac{1}{|G^c|} \int_G \Delta_\xi g_1(x, \xi) d\xi \\ -\Delta_\xi g_1(x, \xi) \end{pmatrix} \quad (45)$$

The operator $-\Delta_\xi$ on G with homogeneous Dirichlet boundary condition has a discrete spectrum $\{\beta_k\}_{k \in \mathbb{N}}$, $\beta_k > 0$, $\beta_k \rightarrow \infty$. We denote by $\varkappa_k(\xi)$, $k = 1, 2, \dots$, the corresponding normalized eigenfunctions and introduce the set \mathbb{N}^* of indices k such that $\int_G \varkappa_k(\xi) d\xi = \langle \varkappa_k \rangle \neq 0$.

Lemma 2.5. *The continuous spectrum $\sigma_{cont}(-A)$ of the operator $-A$ is a countable set of non-overlapping segments*

$$\sigma_{cont}(-A) = \bigcup_{k \in \mathbb{N}^*} [\tilde{\lambda}_k, \beta_k],$$

where $\tilde{\lambda}_1 = 0$, and $\tilde{\lambda}_k$, $k > 1$, is the nearest to β_k solution of equation

$$\frac{1}{|G^c|} \sum_k \frac{\alpha_k^2 \beta_k}{\beta_k - \tilde{\lambda}} + 1 = 0 \quad \text{with} \quad \alpha_k = \langle \varkappa_k \rangle$$

such that $\tilde{\lambda}_k < \beta_k$. The discrete spectrum of the operator $-A$ is the union of eigenvalues β_k with $k \in \mathbb{N} \setminus \mathbb{N}^*$.

Proof. The second line in the equation $-AF = \lambda F$ reads

$$-A(f_0(x) + g_1(x, \xi)) = -\Delta_\xi g_1(x, \xi) = \lambda(f_0(x) + g_1(x, \xi)). \quad (46)$$

The function $f_0(x)$ does not depend on ξ , its Fourier series w.r.t. $\varkappa_k(\xi)$ takes the form $f_0(x) \cdot 1 = f_0(x) \sum_k \alpha_k \varkappa_k(\xi)$. Denoting by γ_k the Fourier coefficients of g_1 , from (46) we get

$$-\Delta_\xi g_1(x, \xi) = \sum_k \beta_k \gamma_k \varkappa_k(\xi) = \lambda f_0(x) \sum_k \alpha_k \varkappa_k(\xi) + \lambda \sum_k \gamma_k \varkappa_k(\xi).$$

Consequently, for any $\lambda \notin \{\beta_k\}$ we have $\gamma_k = \lambda f_0(x) \frac{\alpha_k}{\beta_k - \lambda}$, and thus the function

$$g_1(\xi) = \sum_k \gamma_k \varkappa_k(\xi) = \lambda f_0(x) \sum_k \frac{\alpha_k}{\beta_k - \lambda} \varkappa_k(\xi), \quad (47)$$

is a solution of equation $-A(f_0 + g_1) = -\Delta_\xi g_1 = \lambda(f_0 + g_1)$ for any $\lambda \notin \{\beta_k\}$.

Inserting (47) in the first line of the equation $-AF = \lambda F$ yields

$$-\Theta \nabla \nabla f_0(x) - \lambda f_0(x) \frac{1}{|G^c|} \sum_k \frac{\alpha_k \beta_k}{\beta_k - \lambda} \int_G \varkappa_k(\xi) d\xi = \lambda f_0(x).$$

We conclude that

$$-\Theta\nabla\nabla f_0(x) = \lambda f_0(x) \left(\frac{1}{|G^c|} \sum_k \frac{\alpha_k \beta_k}{\beta_k - \lambda} < \varkappa_k > + 1 \right) = \lambda f_0(x) \left(\frac{1}{|G^c|} \sum_k \frac{\alpha_k^2 \beta_k}{\beta_k - \lambda} + 1 \right). \quad (48)$$

Since the spectrum of the operator $-\Theta\nabla\nabla$ fills up the positive half-line, we obtain that all $\lambda > 0$ such that

$$\frac{1}{|G^c|} \sum_k \frac{\alpha_k^2 \beta_k}{\beta_k - \lambda} + 1 \geq 0$$

belong to the spectrum of the operator $-A$. One can easily check that the segment $[0, \beta_1]$ belongs to the continuous spectrum of $-A$. This implies the desired statement on $\sigma_{cont}(-A)$.

It is straightforward to check that for all $k \in \mathbb{N} \setminus \mathbb{N}^*$ the functions $(0, \varkappa_k(\xi))$ are eigenfunctions of $-A$. This completes the proof. \square

Proposition 2.1. *If $\lambda \in \sigma(-A)$, then λ is the limit of a sequence of points from the spectra of operators A_ε , i.e. $\forall \delta > 0 \exists \varepsilon_0 > 0$ such that there exists $\lambda_\varepsilon \in \sigma(-A_\varepsilon) \cap O_\delta(\lambda)$ for all $\varepsilon < \varepsilon_0$.*

Proof. Since $\lambda \in \sigma(-A)$, there exist functions $F_n \in D_A$ with $\|F_n\| = 1$ such that $\|(A - \lambda)F_n\| \rightarrow 0$ as $n \rightarrow \infty$. Using the approximation theorem we additionally have that for any $F_n \in D_A$ there exists $F_n^\varepsilon \in D(A_\varepsilon)$ such that

$$\|F_n^\varepsilon - F_n\| \rightarrow 0 \quad \text{and} \quad \|A_\varepsilon F_n^\varepsilon - A F_n\| \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

Thus we obtain that for any (small) $\delta > 0$ there exists $\varepsilon_0 = \varepsilon_0(\lambda) > 0$ such that

$$\|A_\varepsilon F_n^\varepsilon - \lambda F_n^\varepsilon\| < \delta \quad \text{for all } \varepsilon < \varepsilon_0. \quad (49)$$

This implies that there is a point of the spectrum of A_ε in the δ -neighbourhood of λ . \square

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