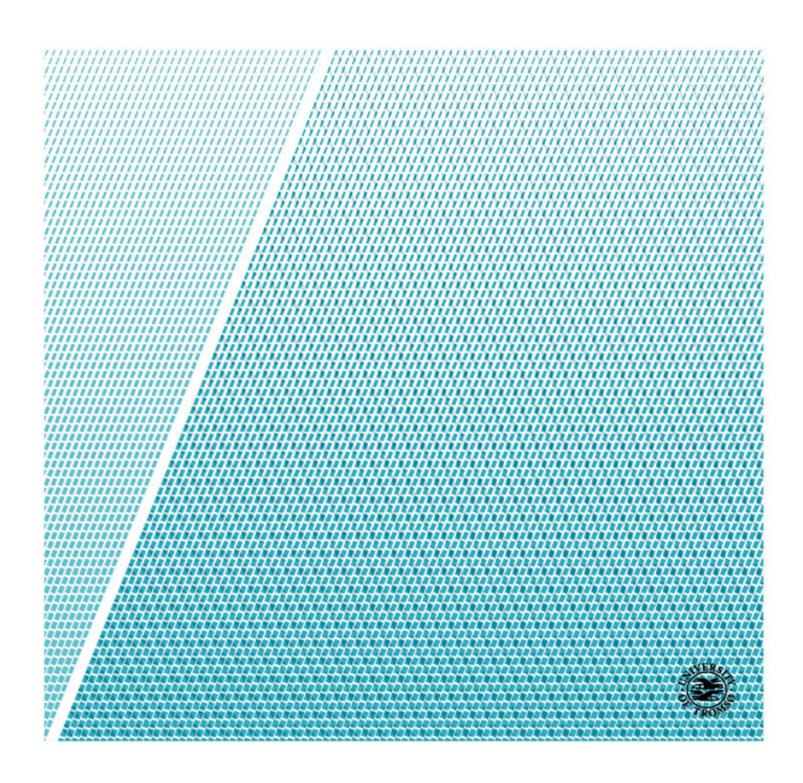


Faculty of Engineering Science and Technology (IVT) Department of Industrial Engineering

The Pre Study Report Thin Wall Structure by Welding

Stud. Techn. Hans Ivar Arumairasa





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This Pre study give insight in the thesis subject of thi	n wall structure, how its					
organized and implemented over 19 weeks, importan	t milestones and what the study will result in					

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1 Introduction

1.1 Introduction

The master thesis is divided into two parts. Part one is a literature review where information and research of the topic are collected to gain a platform of basic knowledge where the further work in part two is based on. During the next part of the thesis is the actual work conducted and documented which the result is built on.

The study entails about manufacture thin wall structure by welding which is a more economic and faster way of production than standard milling and machining. It generates growth in relation to engineering structures, with areas from aircraft, bridges, ships and general complex and large structures. The thin wall structure is an arc-based deposition process of a thin wall structure in a layer upon layer manner, which is conducted by a technique of Additive Manufacturing [AM]. AM are commonly known as 3D-printing technology with a waste specter of different methods, however, this study will utilize GTAW-Based Wire Arc Additive Manufacturing System to weld the component, explained in the figure below [1].

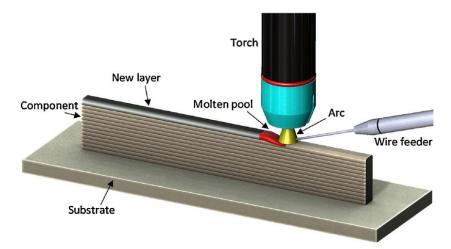


Figure 1: GTAW-Based Wire Arc Additive Manufacturing System. Source [1]

Figure 1 describe the process of GTAW-Based Wire Arc Additive Manufacturing that produces a thin wall structure. Short described: a process where a wire of a given material is fed beneath the tungsten arc to be melted under the molten pool which generates layers of deposition. The layer is welded on top of each other until a component is produced. This study of welding technology (3D-printing) aim for utilizing GTAW-based wire arc additive manufacturing which is conducted by a KUKA-KR30-3 robot to produced an optimal thin structure. A method of measure the residual stresses then take place to find out how much stresses (tensile) the component contains. All samples made are documented by a welding procedure qualification record (WPQR), it represents how the component was made and its property after production. When the activity "robot welding" and "residual stress test" are completed, a digital simulation method by the software "ANSYS" are used to give an analytic overview of the results. A comparison of the digital analyzes and the practical result are then presented to conclude the thesis's outcome.

1.2 Background

Reason for choosing this thesis subject is based on my earlier experience at welding in a job context, robotic subject from earlier in our thesis program also woke my interest in this world of technology. The thesis was handed out from the University of Tromsø campus Narvik, who wanted to achieve further result and documentation of robotic welding. Especially when the topic of thin walls structure is a low documented theme which has global increasing popularity of technology within the additive manufacturing [2].

1.3 Problem statement

Problem statement: Most productions of today's structure component are in general generated by subtracting machining. To achieve a more complex and efficient production, the 3Dprinting technology by additive manufacturing is utilized: welding of thin wall structures by additive manufacturing. During the GTAW process thermal and mechanical distortion occurs and creates residual stresses, shrinkage and tension, which can compromise and decrease the structure's tensile strength and grain structure. To control or to minimize the residual stress, stress distribution is needed to be known.

1.4 Assumptions and project framework

Prerequisites and framework for the project contain limitation within the lab works as welding process and tensile stretch bench. The alloys of stainless steel 3041 and X3CrNiMo13-4 are assumed to provide wide enough specter of a different outcome to compare and lay a basis for discussion and result. Since there are just the material X3CrNiMo13-4 that need PWHT (Post Weld Heat Treatment) it is predicted that the material property of the thin wall structure is equal to the original material before welding. The last assumption regards preheating, where a portable torch are used to generate enough energy to heat up the material to an acceptable level The project contains a framework of the experimental part of the study. This includes the welding process, strength, and fatigue -tests and analyses of the produced thin wall structure, which is documented by the welding procedure qualification record which is the framework in written form.

2 Effect goal and results

This section provides knowledge of the study's purpose, what the involved parties gain from it, how long the project is and potential costs.

2.1 Effect Goal

The profit from this study is to gain a solid procedure and a documented analysis of the thin wall structure process, for the University of Tromsø. It strengthens the school's knowledge in the new 3D-printing technology (AM) which further can be developed by the school's resources as in lab projects or for future master's/doctor's degree studies. This could further

affect the school's reputation for welding/robotic-technology that could attract interest for upcoming students and researchers around the world.

2.2 Outcome and Scope

2.2.1 Objective for results

The main outcome of the thesis are to find the measurement of the residual stresses in the thin wall structure. This study will result in these concrete tasks:

- Conduct a welding experiment with a mixture and manipulation of parameters, design of weld and thermal and mechanical process techniques to produce thin wall structures.
- Study, analyze and identify residual stresses and distortion in weld.
- Develop an optimal procedure process which contain documentation of the thin wall structure process and compare it to a digital simulation model.
- Carry the documents in written form

2.2.2 Time frames

The study report is to be expected done within 30 May 2019 in week 22, where the thesis will be conducted over 21 weeks period.

2.2.3 Costs

In this study are there no direct costs except the material and equipment the school provide at the lab.

2.3 Theory/hypothesis

The theory/hypothesis of the thesis is to use the 3D-printing technology of GTAW-based WAAM system to make a component/structure that have preserved/ improved its property in the material after the weld. The welded structure is expected to consists of a homogeneous weld that has more endurance and strength than the original material. The result of the product is to have an reduced amount of residual stress and has a limited amount of distortion (deformation/shrinkage) in the base plate if the preheating and PWHT is done right.

3 Implementation and Organization

3.1 Project phases / main activities

Activity	Name:	Purpose:	Results:				
A	Project Manage-	Weekly planning and monitoring the	Gain overview in the time schedule				
Π	ment	progress at the study's result.	to plan weekly goals.				
		Selection of the best concept to weld					
В	Concept Phase	structures design to compare with the	Concepts structure sketched in Inventor.				
		originally thin wall structure					
			An developed optimal procedure to weld				
C	Robot welding	Produce thin wall structure by use of	an thin wall structure by use of				
	Robot weiding	robotic GTAW technology.	KUKA-30-3 robot and create different				
			design.				
D	Residual stress	Examine residual stresses in the componen	An graph that shows the components				
	test	Examine residual suesses in the component	stresses (tensile).				
		Provide an digital point of	Gain an illustrated figure of the different				
E	ANSYS	view with the FEA-method to compare	concept design and provide an digital				
		with the practical results.	analyze.				
		Gather and analyze the data from the	Draw an discussion and conclusion from				
F	Analyze data	lab test and compare to the results from	the analyzed data if the structure are				
		ANSYS.	sustainable.				
		Documentation of the study in its entirety.					
G	Report writing	The report is the result of the entire	The finally project report.				
U	Report writing	project and is considered the most	The many project report.				
		important part.					
Н	Prepare presenta-	Complete a part of the project, present the	Make an PowerPoint presentation				
11	tion	progressed work.	ware an i owen onit presentation				
Ι	Complete Report	Control the content, typo, layout etc	Final controlled report.				

Table 1: Main activities

3.1.1 Milestones

Milestones:	Date:	Description:				
Project start	11.01.2019	Starting the project, delivering the task				
Determination of concept	20.01.2019	Determine the design of the structure				
Finish the lab tests	22.02.2019	Finish with weld and				
Fillish the lab tests	22.02.2019	tests of thin wall structures				
Simulate in ANSYS	31.03.2019	Analyze the component and				
Simulate in ANS IS	51.05.2019	present as digital data.				
Complete the report	28.05.2019	Write and finalize the report.				

Table 2: Milestones

3.1.2 Submission and status dates

Submissions during the Master Thesis:	Date:	Description:
Project start- part 2:	14.01.2019	Delivery of Master thesis
110jeet start- part 2.	14.01.2019	description Part 2.
Pre-study report	05.02.2019	Delivery of pre-study
Status meeting 2	13.02.2019	Mandatory status meeting
Status meeting 3	20.03.2019	Mandatory status meeting
Status meeting 4	10.04.2019	Mandatory status meeting
Status meeting 5	15.05.2019	Mandatory status meeting
Last oral presentation	31.05.2019	Presentation of final work.
Final Report	31.05.2019	Delivery of end report

Table 3: Dates of status delivery

3.1.3 Decision points

Decision point:	Date:	Decription:
First draft of concept	16.01.2019	Make different suggestion as structure design to weld
Completed concept	20.01.2019	Deside three design to produce.

Table 4: Dates of decisions

3.2 Progress monitoring

It's worked out a detailed plan for the project, to monitor planned hours compared to actual hours done for each week and activity. This is presented by a time schedule, Gant-diagram, an S-curve. Time schedule shows all activity that is planned, how many hours the different week have at different activities and how much of the project that is left. The Gant-diagram are based on the time schedule activities that present the data in a column chart. It provides precise data of each activities starting week, and the length of it in weeks compare to other activities and the total length of the project. The S-curve presents how many hours are planned at given weeks in percent. Data from the S-curve and Gant-chart are presented as planned in the pre-study report where it later compared to actual progress in the status meetings and in the end report. The time schedule (with actual hours done) are updated for every week in the study

3.3 Status reporting

Every status report that is presented in table 3, are based on progressed work compare to the planned work addressed in this study report. During this master, there is five status meeting and total six representations.

4 Risk Analyses

4.1 Critical success factor

As a part of the HSE work in the lab at UiT, a risk analysis has been developed to map thoroughly high potentially cause injuries or illness in the workplace. The Norwegian Working Environment Act requires that all businesses performing this analysis have three simple tips that are the core of risk assessment:

- What can go wrong?
- What can we do to prevent this?
- What can we do to reduce the consequences if this happens?

In order to assess the risk, a critical success factor is used to classify the risks:

$$Probability \times consequence = Risk factor \tag{1}$$

Consequence: Probability:	1. Insignificant	2. Less serious/ A certain danger	3. Considerable/ Critical	4. Severe / dangerous	5. Very serious/ disastrous
5. Extremely likely	5	10	15	20	25
4. Very likely	4	8	12	15	20
3. likely	3	6	9	12	15
2. Less likely	2	4	6	5	10
1. Little likely	1	2	3	4	5

Figure 2: Critical success factor spectre. Source: [3]

The risk analysis is presented by figure 3 which shows unwanted events that are inflicted by possible cause and result as a consequence that impacts the progress of the project. The consequences are based on a risk factor which consists of a specter between 1-25 as shown in figure 2. The red area at the top of the corner indicates the severity of the danger while the yellow color in the middle of the specter indicates less serious/danger to the project's progress. At last the green color at the left corner indicates an insignificant degree of danger. Probability and consequence have a factor of range one to five that indicates the severity.

Explanation of figure 3, the specter of critical success factors. If risk number four should occur that present a possible unwanted event of "defect part" (the component that has distortion and high tension), would it be inflicted by a possible cause of thermal or mechanical processes which would risk progressed and achieved goals of the project. The degree of probability for this to occur was set to five and the consequence to three which generate a risk factor of 15. The risk factor is located in the severity part of the specter in figure 2. An action is therefore implemented to conduct either preheating, welding sequence or post-welding heat treatment. This is due to prevent distortion and tension in component (defect). Thus will the probability for the situation to occur reduced to three and the consequence to 2 which result at a risk factor at six which is less danger.

Risk			Possil	ole unwanted event	Possible cause	Conse	equ	enc	e			
1				Absence	Disease, travel,							
					job or potential							
			T	or::	injury							
2			Insu	fficient expertise.	Low knowledge							
					of the process and general low							
					expertise in							
					welding.	F	Risk	ing				
3		Weld	ling bl	lindness or heat damage	Not wearing	prog	res	s in	the			
					welding mask.	-	oroj	-				
4				Defect parts	Thermal or	achie						
					mechanical	and	adl					
5			Net 1	omogonoous wald	processes Not enough	ae	adl	ine	5.			
5			not n	omogeneous weld	Not enough sufficient welded.							
					Wrong parameters							
6		Com	oromi	se the component during	Machining the							
				sidual stress test	thin wall							
					structures							
7	I			inish the activity at the lab	Errors with the							
		and fi	nd a v	vay to test residual stress	robot during							
					welding and travel							
8	1	Rahat	faile	to conduct the operation.	to China. Equipment							
0	·	KUUU	alls	to conduct the operation.	malfunction, short							
					circuit.							
	Р	С	R	Acti	ons		Р	С	R			
		essment efore act							nent of action			
1	2	3	6	Prioritize away partying, h	olidays and excursion	1s in	1	3	3			
				the coming semester. Avoid								
				at the gym.								
2	3	4	12	Seek in literature revi	ew or tips/help f	from	1	4	4			
2	5	5	25	professionals (professors)	4 C-11 TICE	1.	2	2	-			
3	5	5	25	Use mask equipment an	dure	2	3	6				
4	5	3	15	Attention at preheating w	elding sequence and	post	3	2	6			
T		-		welding heat treatment	Attention at preheating, welding sequence and pos welding heat treatment							
5	3	5	15		Use standard parameters used in earlier operation of							
				robot welding as basep								
				experience.								
6	4	4	16	Careful with machining, co			5	2	10			
7	3	5	15	Meet at school earlier and	-		2	2	4			
				08:00 to 16:00 AM. Call of	her universities to con	duct						
8	2	5	10	the residual stress activity	moonant and proc	tical	2	2	4			
0	2	5	10	Double check every co procedure before welding.	mponent and prac	acai	2	2	4			
				procedure before weiding.		[

Figure 3:	Critical	success	factor.	Source:	[3]
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5 Costs

5.1 Planned amount of time

There is no direct cost related to the thesis. However, a budget is set up regarding student's hours used. In total has each student 1200 hours to spend, where 400 hours are for the literature review and around 800 hours for part two which is the main part of the thesis. This project's part two are based on 828 planned hours in total where the main priority lies at activity "Robot welding" (136h) and "report writing" (209h).

5.2 Cost / Benefit

The task is built on a theoretical and a practical part. The practical part includes lab activities which are used to develop a procedure of qualification to achieve an optimal procedure of a thin wall structure by robotic welding. The procedure process, in this case, results as the reward/benefit of the study, along with the analytic knowledge where the lab-result are compared with. This gives the school knowledge in future 3D-printing technology by welding.

6 Quality management, HSE and Monitoring

6.1 Quality management

Good quality management from the start of the project, the UiT, and the student-facilitated has implemented a new orientation structure. It is therefore added a solid procedure of frequently mandatory status meetings and presentation of progressed work to ensure positive progress and more fluent implementation of the project. This would also result in a close follow-up of the requirements specifications from the task description part two and by NS 9001: 2008. During the project, especially under the lab-test activity will regularly contact with supervisor be attended to make sure quality management during the riskiest phase in this study.

6.2 HSE

Health, security, and environment (HSE) are important factors that impact the project's progress and results. As a part of HSE-evaluation, it is prepared a risk to analyze internally in the project as shown in figure 3. In the critical success, factor analyzes risk number three takes a dangerous situation that can occur into account and which action to take which result in a lower risk factor.

Regarding HSE some point of view are taken into account to prevent potentially HSE problems:

- Use protection equipment as welding mask and cloth that cover the surface of the skin
- Not enter the welding area while the robot are working

• Secure the welding equipment before and after welding (example cut the filler metal after weld)

6.3 Monitoring

During the project phase has the student together with the supervisor agreed to have electronic status meetings through Skype, because of the distance from China. Possible meetings beside the mandatory status presentations need to be a planned appointment in the supervisor's favor. This is done to avoid unnecessary costs in form of work with unwanted concepts. Otherwise, will future work in China be discussed with the supervisor provided by Bejing Institute of Technology, which will be an internal arrangement.

Following attaqchments will be added in to the pre-study:

- Time schedule
- Gant-diagram
- S-curve
- Activity descriptions (10 descriptions, one for each activity)

Planned				Weeks											China								
Activity																							
	Starting week	Length in weeks	Hours	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22
Project start																							
	3	1	10	10																			
Project	3	20	43	5	2	2	2	2	2	2	2	2	2		2	2	2	2	2	2	2	2	2
Management	5	20	45	3	2	2	2	2	2	2	2	۷	2	2	2	۷	2	2	۷	2	۷	2	2
Concept phase	3	1	15	15																			
Robot welding																							
	4	5	136		30	30	30	30	16														
Residual stress																							
test	4	5	50		10	10	10	10	10														
ANSYS																							
	9	5	125							25	25	25	25	25									
Analyze data	14	4	120												30	30	30	30					
Report writing																							
	3	17	209	10	10	8	7	5	5	12	12	12	12	20	12	12	12	20	20	20			
Prep.Presentation																							
	5	6	60			5	10	5				5	5		5	5				5	5	5	5
Complete report																							
	20	3	60																		20	20	20
Total for Project:																							
	· · · · · · · · · · · · · · · · · · ·		828	40	52	55	59	52	33	39	39	44	44	47	49	49	44	52	22	27	27	27	27
Plan.Hours(acc)				40	92	147	206	258	291	330	369	413	457	504	553	602	646	698	720	747	774	801	828
Plan.progress(%)				10	52	211	200	200		000		.10		0.04	000	002	0.0	0.50	. 20				020
				4,831	11,11	17,75	24,88	31,16	35,14	39,86	44,57	49,88	55,19	60,87	66,79	72,71	78,02	<mark>84,</mark> 3	86,96	90,22	93,48	96,74	100

Figure 4: Attachment 1. Time schedule

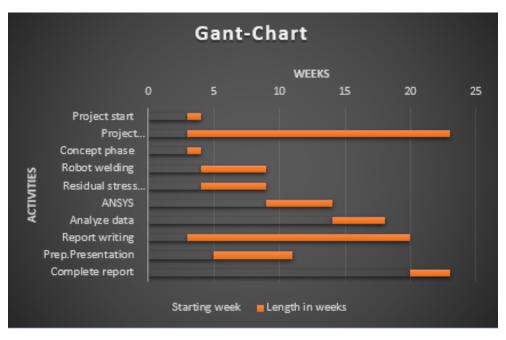


Figure 5: Gant-Diagram





Project title:	Sign:	Date:	
Thin Wall Structure by Welding		17.01.2019	
Activity name:	Activity Nr:		
Project Management	Nr. A		
Responsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Weekly planning and quality management to monitor progression			
Scope:			
Start of every week some hours are use to monitor progressed work and compare the			
actual work to the planned onces. Then a weekly planning will be conducted to manage			
the time frame and ensure everything will be done.			
Method:			
Excel in form of S-curve and update on the actual time schedule			
Dependency:			
On progressed work and pre-study			
Documentation/results:			
Documented in Latex (pdf)			
Written by:	Duration:		
Hans Ivar Arumairasa	20 weeks		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		17.01.2019	
Activity name:	Activity Nr:		
Concept Phase	Nr. B		
Responsible:	·		
Hans Ivar Arumairasa			
Task Description/intention:			
Make an design of the thin wall structure to be welded in t	he lab-test activ	vity.	
Scope:			
Create multiple design in the software Inventor and then u	se a conceptual	ization analyze	
to choose the best designs to be welded. Afterwards a com	parison of the	original one then	
take place to show differences in its properties.			
Method:			
Inventor			
Dependency:			
The pre-study			
Documentation/results:			
Concept sketch will be documented and evaluated in the report (Latex).			
Results are evaluated in tables included drawings.			
Written by:	Duration:		
Hans Ivar Arumairasa	1 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		21.01.2019	
Activity name:	Activity Nr:		
Robot welding	Nr. C		
Responsible:	1		
Hans Ivar Arumairasa			
Task Description/intention:			
Weld up thin wall strucutres to conduct residual stress testes on.			
Scope:			
The robot KUKA-30-3 are used to weld an thin wall struct	ture with given	parameters.	
When the right parameters are found, different design are created to generate			
different outcome.			
Method:			
GTAW-based WAAM process by KUKA-30-3 robot in the lab.			
Dependency:			
Concept Phase			
Documentation/results:			
Documented by the procedure called WPQR (welding procedure qualification			
record) in the pdf (latex) Result are the component produced and the optimized procedure.			
Written by: Duration:			
Hans Ivar Arumairasa	5 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		21.01.2019	
Activity name:	Activity Nr:		
Residual stress test	Nr. D		
Responsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Examine the residual stresses at the surface the weld and material.			
Scope:			
Find a methods of measure the residual stresses in weld. Collect samples of stresses at the			
weld and material and represent the data in form of a graph.			
Method:			
Non-destructive, semi-destructive or destructive test			
Dependency:			
Lab welding			
Documentation/results:			
Documented by the procedure called WPQR (welding procedure qualification			
record) in latex.			
Written by:	Duration:		
Hans Ivar Arumairasa	5 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		25.02.2019	
Activity name:	Activity Nr:		
ANSYS	Nr. E		
Resbonsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Conduct an FEA analyze method to gain an illustration of	possible high s	tress and distortion	
in baseplate and structure component.			
Scope:			
Conduct an FEA analyze where the geometry of the structure	ures created in	Inventor are	
transferred to ANSYS to generate an stress and displacement	ent analyze.		
Method:			
ANSYS			
Dependency:			
Lab tests and Concept Phase			
Documentation/results:			
Documented in latex.			
Result provides an illustrated figures of the different concepts design and			
contribute an digital analyze.			
Written by:	ritten by: Duration:		
Hans Ivar Arumairasa	5 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		21.01.2019	
Activity name:	Activity Nr:		
Analyzed data	Nr. F		
Resbonsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Gather and analyze the data from the lab test (WPQR) and	compare to the	e results simulated	
from ANSYS.			
Scope:			
Compare the difference in the data from the simulation and	d to the actual d	lata provided in the	
lab. Followed by documentation why the result occurred as they did and provide an analyze			
that shows if the thin wall structure was successfully.			
Method:			
Latex			
Dependency:			
Lab tests and ANSYS			
Documentation/results:			
Documented in latex with tables and analyzes. Result contains material to discuss and draw an			
conclusion from the analyzed data.			
Vritten by: Duration:			
Hans Ivar Arumairasa	4 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		18.01.2019	
Activity name:	Activity Nr:		
Report writing	Nr. G		
Responsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Documentation of the project in its entirety and conclusion. The report is the result of the			
entire project and is considered the most important part.			
Scope:			
Write documentation of hypothesis/theory and result from the other activities which will			
be conducted some hours every week.			
Method:			
Latex			
Dependency:			
Result from other activities			
Documentation/results:			
Documented in latex. Result in a final report of the thesis study.			
Written by:	Duration:		
Hans Ivar Arumairasa	17 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		30.01.2019	
Activity name:	Activity Nr:	•	
Prep.Presentation	Nr. H		
Responsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Complete a part of the project, present the progressed work.			
Scope:			
Conduct an PowerPoint presentation of the work from last submission.			
Method:			
PowerPoint			
Dependency:			
Result in the progressed work from other activities			
Documentation/results:			
Documented in latex. Result in a PowerPoint presentation of the progressed work.			
Written by:	Duration:		
Hans Ivar Arumairasa	17 week		

Project title:	Sign:	Date:	
Thin Wall Structure by Welding		13.05.2019	
Activity name:	Activity Nr:		
Complete report	Nr. I		
Responsible:			
Hans Ivar Arumairasa			
Task Description/intention:			
Control the content, typo, layout before deliver the final re-	port		
Scope:			
Read over the document several times and ensure a secound party also read the final report.			
Method:			
Latex			
Dependency:			
Report writing			
Documentation/results:			
Documented in latex. Result as a final report.			
Written by:	Duration:		
Hans Ivar Arumairasa	3 week		

References

- [1] Vladimir Luzin and Nicholas Hoye. "Stress in Thin Wall Structures Made by Layer Additive Manufacturing". In: (July 2016). DOI: 10.21741/9781945291173-84.
- [2] R.J. Silva, G.F. Barbosa, and J. Carvalho. "Additive Manufacturing of Metal Parts by Welding". In: *IFAC-PapersOnLine*. Volume 48.3 (2015). 15th IFAC Symposium onInformation Control Problems inManufacturing, pp. 2318–2322. ISSN: 2405-8963. DOI: https: //doi.org/10.1016/j.ifacol.2015.06.433. URL: http://www. sciencedirect.com/science/article/pii/S2405896315006722.
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